**clustMixType: User-Friendly Clustering of Mixed-Type Data in R**

*by Gero Szepannek*

**Abstract** Clustering algorithms are designed to identify groups in data where the traditional emphasis has been on numeric data. In consequence, many existing algorithms are devoted to this kind of data even though a combination of numeric and categorical data is more common in most business applications. Recently, new algorithms for clustering mixed-type data have been proposed based on Huang’s k-prototypes algorithm. This paper describes the R package `clustMixType` which provides an implementation of k-prototypes in R.

**Introduction**

Clustering algorithms are designed to identify groups in data where the traditional emphasis has been on numeric data. In consequence, many existing algorithms are devoted to this kind of data even though a combination of numeric and categorical data is more common in most business applications. For an example in the context of credit scoring, see, e.g. Szepannek (2017). The standard way to tackle mixed-type data clustering problems in R is to use either (1) Gower distance (Gower, 1971) via the `gower` package (van der Loo, 2017) or the `daisy(method = "gower")` in the `cluster` package (Maechler et al., 2018); or (2) Hierarchical clustering through `hclust()` or the `agnes()` function in `cluster`. Recent innovations include the package `CluMix` (Hummel et al., 2017), which combines both Gower distance and hierarchical clustering with some functions for visualization. As this approach requires computation of distances between any two observations, it is not feasible for large data sets. The package `flexclust` (Leisch, 2006) offers a flexible framework for k-centroids clustering through the function `kcca()` which allows for arbitrary distance functions. Among the currently pre-implemented `kccaFamilies`, there is no distance measure for mixed-type data. Alternative approaches based on expectation-maximization are given by the function `flexmixedruns()` in the `fpc` package (Hennig, 2018) and the package `clustMD` (McParland, 2017). Both require the variables in the data set to be ordered according to their data type, and that categorical variables to be preprocessed into integers. The `clustMD` algorithm (McParland and Gormley, 2016) also allows ordinal variables but is quite computationally intensive. The `kamaile` package (Foss and Markatou, 2018) implements the KAMILA clustering algorithm which uses a kernel density estimation technique in the continuous domain, a multinomial model in the categorical domain, and the Modha-Spangler weighting of variables in which categorical variables have to be transformed into indicator variables in advance (Modha and Spangler, 2003).

Recently, more algorithms for clustering mixed-type data have been proposed in the literature (Amir and Dey, 2007; Dutta et al., 2012; Foss et al., 2016; He et al., 2005; HajKacem et al., 2016; Ji et al., 2012, 2013, 2015; Lim et al., 2012; Liu et al., 2017; Pham et al., 2011). Many of these are based on the idea of Huang’s k-prototypes algorithm (Huang, 1998). The rest of this paper describes the R package `clustMixType` (Szepannek, 2018), which provides up to the author’s knowledge the first implementation of this algorithm in R. The k-modes algorithm (Huang, 1997a) has been implemented in the package `klaR` (Weihs et al., 2005; Roever et al., 2018) for purely categorical data, but not for the mixed-data case. The rest of the paper is organized as follows: A brief description of the algorithm is followed by the functions in the `clustMixType` package. Some extensions to the original algorithm are discussed and as well as a worked example application.

**k-prototypes clustering**

The k-prototypes algorithm belongs to the family of partitional cluster algorithms. Its objective function is given by:

\[ E = \sum_{i=1}^{n} \sum_{j=1}^{k} u_{ij} d(x_i, \mu_j), \]

where \( x_i, i = 1, \ldots, n \) are the observations in the sample, \( \mu_j, j = 1, \ldots, k \) are the cluster prototype observations, and \( u_{ij} \) are the elements of the binary partition matrix \( U_{n \times k} \) satisfying \( \sum_{j=1}^{k} u_{ij} = 1, \forall i \).
The distance function is given by:

\[ d(x_i, \mu_j) = \sum_{m=1}^{q} (x_{mi} - \mu_{mj})^2 + \lambda \sum_{m=q+1}^{p} \delta(x_{mi}, \mu_{mj}) \]  

(2)

where \( m \) is an index over all variables in the data set where the first \( q \) variables are numeric and the remaining \( p - q \) variables are categorical. Note that \( \delta(a, b) = 0 \) for \( a = b \) and \( \delta(a, b) = 1 \) for \( a \neq b \), and \( d() \) corresponds to weighted sum of Euclidean distance between two points in the metric space and simple matching distance for categorical variables (i.e. the count of mismatches). The trade off between both terms can be controlled by the parameter \( \lambda \) which has to be specified in advance as well as the number of clusters \( k \). For larger values of \( \lambda \), the impact of the categorical variables increases. For \( \lambda = 0 \), the impact of the categorical variables vanishes and only numeric variables are taken into account, just as in traditional k-means clustering.

The algorithm iterates in a manner similar to the k-means algorithm (MacQueen, 1967) where for the numeric variables the mean and the categorical variables the mode minimizes the total within cluster distance. The steps of the algorithm are:

1. Initialization with random cluster prototypes.
2. For each observation do:
   (a) Assign observations to its closest prototype according to \( d() \).
   (b) Update cluster prototypes by cluster-specific means/modes for all variables.
3. As long as any observations have swapped their cluster assignment in 2 or the maximum number of iterations has not been reached: repeat from 2.

**k-prototypes in R**

An implementation of the k-prototypes algorithm is given by the function

\[
\text{kproto}(x, k, \text{lambda} = \text{NULL}, \text{iter.max} = 100, \text{nstart} = 1, \text{na.rm} = \text{TRUE})
\]

where

- \( x \) is a data frame with both numeric and factor variables. As opposed to other existing R packages, the factor variables do not need to be preprocessed in advance and the order of the variables does not matter.
- \( k \) is the number of clusters which has to be pre-specified. Alternatively, it can also be a vector of observation indices or a data frame of prototypes with the same columns as \( x \). If ever at the initialization or during the iteration process identical prototypes do occur, the number of clusters will be reduced accordingly.
- \( \text{lambda} > 0 \) is a real valued parameter that controls the trade off between Euclidean distance for numeric variables and simple matching distance for factor variables for cluster assignment. If no \( \lambda \) is specified the parameter is set automatically based on the data and a heuristic using the function \text{lambdaest}(). Alternatively, a vector of length \text{ncol}(x)\ can be passed to \text{lambda} (cf. Section on Extensions to the original algorithm).
- \( \text{iter.max} \) sets the maximum number of iterations, just as in \text{kmeans}(). The algorithm may stop prior to \text{iter.max} if no observations swap clusters.
- \( \text{nstart} \) may be set to a value \( > 1 \) to run k-prototypes multiple times. Similar to k-means, the result of k-prototypes depends on its initialization. If \( \text{nstart} > 1 \), the best solution (i.e. the one that minimizes \( E \)) is returned.
- Generally, the algorithm can deal with missing data but as a default \text{NAs} are removed by \text{na.rm = TRUE}.

Two additional arguments, \text{verbose} and \text{keep.data}, can control whether information on missing values should be printed and whether the original data should be stored in the output object. The \text{keep.data=TRUE} option is required for the default call to the \text{summary()} function, but in case of large \( x \), it can be set to \text{FALSE} to save memory.

The output is an object of class "kproto". For convenience, the elements are designed to be compatible with those of class "kmeans":

- \text{cluster} is an integer vector of cluster assignments
- \text{centers} stores the prototypes in a data frame
• size is a vector of corresponding cluster sizes
• withinss returns the sum over all within cluster distances to the prototype for each cluster
• tot.withinss is their sum over all clusters which corresponds to the objective function $E$
• dists returns a matrix of all observations' distances to all prototypes in order to investigate the
  crispness of the clustering
• lambda and iter store the specified arguments of the function call
• trace lists the objective function $E$ as well as the number of swapped observations during
  the iteration process

Unlike “kmeans”, the “kproto” class is accompanied corresponding predict() and summary() methods. The predict.kproto() method can be used to assign clusters to new data. Like many of its
cousins, it is called by

```r
predict(object, newdata)
```

The output again consists of two elements: a vector of cluster assignments and a matrix of
all observations' distances to all prototypes.

The investigation resulting from a cluster analysis typically consists of identifying the differences
between the clusters, or in this specific case, those of the k prototypes. For practical applications
besides the cluster sizes, it is of further interest to take into account the homogeneity of the clusters.
For numeric variables, this can be done by calling the R function summary(). For categorical variables
the representativity of the prototypes is given their frequency distribution obtained by prop.table().
The summary.kproto() method applies these methods to the variables conditional to the resulting
clusters and returns a comparative results table of the clusters for each variable.

The summary is not restricted to the training data but it can further be applied to new data by
calling summary(object, data) where data are new data that will be internally passed to the predict() method on the object of class “kproto”. If no new data is specified (default: data = NULL), the function
requires object to contain the original data (argument keep.data = TRUE). In addition, a function

```r
clpprofiles(object, x, vars = NULL)
```

supports the analysis of the clusters by visualization of cluster profiles based on an object of class
“kproto” and data x. Note that the latter may also have different variables compared to the original
data, such as for profiling variables that were not used for clustering. As opposed to summary.kproto(),
nor new prediction is done but the cluster assignments of the “kproto” object given by object$cluster
are used. For this reason, the observations in x must be the same as in the original data. Via the vars
argument, a subset of variables can be specified either by a vector of indices or variable names. Note
that clprofiles() is not restricted to objects of class “kproto” but can also be applied to other cluster
objects as long as they are of a “kmeans”-like structure with elements cluster and size.

**Extensions to the original algorithm**

For unsupervised clustering problems, the user typically has to specify the impact of the specific
variables on the desired cluster solution which is controlled by the parameter $\lambda$. Generally, small
values $\lambda \sim 0$ emphasize numeric variables and will lead to results similar to standard k-means
whereas larger values of $\lambda$ lead to an increased influence of categorical variables. In Huang (1997b),
the average standard deviation $\sigma$ of the numeric variables is suggested as the choice for $\lambda$ and in some
practical applications in the paper values of $\frac{1}{3}\sigma \leq \lambda \leq \frac{2}{3}\sigma$ are used. The function

```r
lambdaest(x, num.method = 1, fac.method = 1, outtype = "numeric")
```

provides different data based heuristics for the choice of $\lambda$: The average variance $\sigma^2$ (num.method = 1) or standard deviation $\sigma$ (num.method = 2) over all numeric variables is related to the average
concentration $h_{\text{cal}}$ of all categorical variables. We compute $h_{\text{cal}}$ by averaging either $h_m = 1 - \sum p_{mc}$ (fac.method = 1) or $h_m = 1 - \max_c p_{mc}$ (fac.method = 2) over all variables $m$ where $c$ are the
categories of the factor variables. We set $\lambda = \frac{\sigma^t}{h_{\text{cal}}}, t \in \{1, 2\}$ as a user-friendly default choice to prevent
over-emphasizing either numeric or categorical variables. If kproto() is called without specifying
lambda, the parameter is automatically set using num.method = fac.method = 1. Note that this should
be considered a starting point for further analysis; the explicit choice of $\lambda$ should be done carefully
based on the application context.

Originally, $\lambda$ is real-valued, but in order to up- or downweight the relevance of single variables in
a specific application context, the function kproto() is extended to accept vectors as input where each
The formula for distance computation changes to:
\[ d(x_i, p_j) = \sum_{m=1}^{q} \lambda_m (x_{im} - \mu_{jm})^2 + \sum_{m=q+1}^{p} \lambda_m \delta(x_{im}, \mu_{jm}). \] (3)

Note that the choice of \( \lambda \) only affects the assignment step for the observations but not the computation of the prototype given a cluster of observations. By changing the outtype argument into a vector, the function \( \text{lambdaest()} \) returns a vector of \( \lambda_m \)s. In order to support a user-specific definition of \( \lambda \) based on the variables’ variabilities, outtype = “variation” returns a vector of original values of variability for all variables in terms of the quantities described above.

An issue of great practical relevance is the ability of an algorithm to deal with missing values which can be solved by an intuitive extension of k-prototypes. During the iterations, cluster prototypes can be updated by ignoring NAs: Both means for numeric variables as well as modes for factors can be computed based on the available data. Similarly, distances for cluster assignment can be computed for each observation based on the available variables only. This not only allows cluster assignment for observations with missing values, but already takes these observations into account when the clusters are formed. By using \( \text{kproto()} \), this can be obtained by setting the argument na.rm = FALSE. Note that in practice, this option should be handled with care unless the number of missing values is very small. The representativeness of a prototype might become questionable if its means and modes do not represent the major part of the cluster’s observations.

Finally, a modification of the original algorithm presented in Section k-prototypes clustering allows for vector-wise computation of the iteration steps, reducing computation time. The update of the prototypes is not done after each new cluster assignment, but once each time the whole data set has been reassigned. The modified k-prototypes algorithm consists of the following steps:

1. Initialization with random cluster prototypes.
2. Assign all observations to its closest prototype according to \( d() \).
3. Update cluster prototypes.
4. As long as any observations have swapped their cluster assignment in 2 or the maximum number of iterations has not been reached: repeat from 2.

**Example**

As an example, data \( x \) with two numeric and two categorical variables are simulated according to the documentation in \( \text{kproto} \): Using \( \text{set.seed(42)} \), four clusters \( j = 1, \ldots, 4 \) are designed such that two pairs can be separated only by their numeric variables and the other two pairs only by their categorical variables. The numeric variables are generated as normally distributed random variables with cluster specific means \( \mu_1 = \mu_2 = -\mu_3 = -\mu_4 = \Phi^{-1}(0.9) \) and the categorical variables have two levels (A and B) each with a cluster specific probability \( p_1(A) = p_3(A) = 1 - p_2(A) = 1 - p_4(A) = 0.9 \). Table 1 summarizes the clusters. It can be seen that both numeric and categorical variables are needed in order to identify all four clusters.

Given the knowledge that there are four clusters in the data, a straightforward call for k-prototypes clustering of the data will be:

```r
kpres <- kproto(x = x, k = 4)
kpres # output 1
summary(kpres) # output 2
library(wesanderson)
par(mfrow=c(2,2))
clprofiles(kpres, x, col = wes_palette("Royal1", 4, type = "continuous")) # figure 1
```

The resulting output is of the form:

<table>
<thead>
<tr>
<th>cluster</th>
<th>numeric</th>
<th>categorical</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>+</td>
<td>+</td>
</tr>
<tr>
<td>2</td>
<td>+</td>
<td>-</td>
</tr>
<tr>
<td>3</td>
<td>-</td>
<td>+</td>
</tr>
<tr>
<td>4</td>
<td>-</td>
<td>-</td>
</tr>
</tbody>
</table>

Table 1: Separation of clusters in the example.
# Output 1:

Numeric predictors: 2  
Categorical predictors: 2  
Lambda: 5.52477

Number of Clusters: 4  
Cluster sizes: 100 95 101 104  
Within cluster error: 332.909 267.1121 279.2863 312.7261

Cluster prototypes:

<table>
<thead>
<tr>
<th></th>
<th>x1</th>
<th>x2</th>
<th>x3</th>
<th>x4</th>
</tr>
</thead>
<tbody>
<tr>
<td>92</td>
<td>A</td>
<td>A</td>
<td>1.4283725</td>
<td>1.585553</td>
</tr>
<tr>
<td>54</td>
<td>A</td>
<td>A</td>
<td>-1.3067973</td>
<td>-1.091794</td>
</tr>
<tr>
<td>205</td>
<td>B</td>
<td>B</td>
<td>-1.4912422</td>
<td>-1.654389</td>
</tr>
<tr>
<td>272</td>
<td>B</td>
<td>B</td>
<td>0.9112826</td>
<td>1.133724</td>
</tr>
</tbody>
</table>

# Output 2 (only for variable x1 and x3):

x1

<table>
<thead>
<tr>
<th>cluster</th>
<th>A</th>
<th>B</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>0.890</td>
<td>0.110</td>
</tr>
<tr>
<td>2</td>
<td>0.905</td>
<td>0.095</td>
</tr>
<tr>
<td>3</td>
<td>0.069</td>
<td>0.931</td>
</tr>
<tr>
<td>4</td>
<td>0.144</td>
<td>0.856</td>
</tr>
</tbody>
</table>

x3

<table>
<thead>
<tr>
<th></th>
<th>Min.</th>
<th>1st Qu.</th>
<th>Median</th>
<th>Mean</th>
<th>3rd Qu.</th>
<th>Max.</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>-0.7263</td>
<td>0.9314</td>
<td>1.4080</td>
<td>1.4280</td>
<td>2.1280</td>
<td>4.5110</td>
</tr>
<tr>
<td>2</td>
<td>-3.4200</td>
<td>-1.9480</td>
<td>-1.3170</td>
<td>-1.3070</td>
<td>-0.6157</td>
<td>2.2450</td>
</tr>
<tr>
<td>3</td>
<td>-4.2990</td>
<td>-2.0820</td>
<td>-1.4600</td>
<td>-1.4910</td>
<td>-0.7178</td>
<td>0.2825</td>
</tr>
<tr>
<td>4</td>
<td>-1.5300</td>
<td>0.2788</td>
<td>0.9296</td>
<td>0.9113</td>
<td>1.5000</td>
<td>3.1480</td>
</tr>
</tbody>
</table>

The first two as well as the last two cluster prototypes share the same mode in the factor variables but they can be distinguished by their location with respect to the numeric variables. For clusters 1 & 4 (as opposed to 2 & 3), it is vice versa. Note that the order of the identified clusters is not necessarily the same as in cluster generation. Calling summary() and clprofiles() provides further information on the homogeneity of the clusters. A color palette can be passed to represent the clusters across the different variables for the plot; here it is taken from the package wesanderson (Ram and Wickham, 2018).

By construction, taking into account either only numeric (k-means) or only factor variables (k-modes) will not be able to identify the underlying cluster structure without further preprocessing of the data in this example. A performance comparison using the Rand index (Rand, 1971) as computed by the package clusteval (Ramey, 2012) results in rand indices of 0.728 (k-means) and 0.733 (k-modes). As already seen above, the prototypes as identified by clustMixType do represent the true clusters quite well, as the corresponding Rand index improves to 0.870.

library(klaR)
library(clusteval)

kmres <- kmeans(x[,3:4], 4)  # kmeans using numerics only
kmores <- kmodes(x[,1:2], 4) # kmodes using factors only

cluster_similarity(kpres$cluster, clusid, similarity = "rand")
cluster_similarity(kmres$cluster, clusid, similarity = "rand")
cluster_similarity(kmores$cluster, clusid, similarity = "rand")

The runtime of kproto() is linear in the number of observations (Huang, 1997b) and thus it is also applicable to large data sets. Figure 2 (left) shows the behaviour of the runtime for 50 repeated simulations of the example data with an increased number of variables (half of them numeric and
It is possible to run `kproto()` for more than hundred variables which is far beyond most practical applications where human interpretation of the resulting clusters is desired. Note that `clustMixType` is written in R and currently no C++ code is used to speed up computations which could be a subject of future work.

In order to determine the appropriate number of clusters for a data set, we can use the standard scree test. In this case, the objective function $E$ is given by the output’s `tot.withinss` element. The `kproto()` function is run multiple times for varying numbers of clusters (but fixed $\lambda$) and the number of clusters is chosen as the minimum $k$ from whereon no strong improvements of $E$ are possible. In Figure 2 (right), an elbow is visible at the correct number of clusters in the sample data; recall that we simulated from four clusters. Note that from a practitioner’s point of view, an appropriate solution requires clusters that are well represented by their prototypes. For this reason, the choice of the number of clusters should further take into account a homogeneity analysis of the clusters as returned by `summary()`, `clprofiles()` or the `withinss` element of the “kproto” output.

```r
Es <- numeric(10)
for(i in 1:10){
  kpres <- kproto(x, k = i, nstart = 5)
  Es[i] <- kpres$tot.withinss
}
plot(1:10, Es, type = "b", ylab = "Objective Function", xlab = "# Clusters", main = "Scree Plot") # figure 2
```

![Figure 2: Scree Plot](image)

![Figure 2: Runtime for increasing number of variables (left) and screeplot (right).](image)
Summary

The clustMixType package provides a user-friendly way for clustering mixed-type data in R given by the k-prototypes algorithm. As opposed to other packages, no preprocessing of the data is necessary, and in contrast to standard hierarchical approaches, it is not restricted to moderate data sizes. Its application requires the specification of two hyperparameters: the number of clusters $k$ as well as a second parameter $\lambda$ that controls the interplay of the different data types for distance computation. As an extension to the original algorithm, the presented implementation allows for a variable-specific choice of $\lambda$ and can deal with missing data. Furthermore, with regard to business purposes, functions for profiling a cluster solution are presented.

This paper is based on clustMixType version 0.1-36. Future work may focus on the development of further guidance regarding the choice of the parameter $\lambda$, such as using stability considerations (cf. Hennig, 2007), or the investigation of possible improvements in computation time by integrating Rcpp (Eddelbuettel et al., 2018; Eddelbuettel and François, 2011).

Bibliography


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