

# GenMarkov: Modeling Generalized Multivariate Markov Chains in R

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## Supplementary Materials

Consider the following proposed model:

$$P(S_{jt} = i_0 | S_{1t-1} = i_1, \dots, S_{st-1} = i_s, \mathbf{x}_t) \equiv \lambda_{j1}P(S_{jt} = i_0 | S_{1t-1} = i_1, \mathbf{x}_t) + \dots + \lambda_{js}P(S_{jt} = i_0 | S_{st-1} = i_s, \mathbf{x}_t) \quad (1)$$

s.t.  $\sum_{k=1}^s \lambda_{jk}$  and  $\lambda_{jk} \geq 0$ .

The following Proposition holds the consistency of the MLE estimator:

**Proposition 1.** Let  $\{\mathbf{w}_t\}$  be ergodic stationary random variable, with likelihood function  $f(\mathbf{w}_t | \theta_0)$ . Let  $\hat{\theta}$  be the MLE estimator. Suppose that:

1.  $E[\log f(\mathbf{w}_t | \theta_0)]$  is uniquely maximized on  $\Theta$  at  $\theta_0 \in \Theta$ ,
2.  $\theta_0 \in \Theta$ , which is compact,
3.  $\log f(\mathbf{w}_t | \theta_0)$  is continuous at each  $\theta \in \Theta$  with probability one,
4.  $E[\sup_{\theta \in \Theta} |\log f(\mathbf{w}_t | \theta)|] < \infty$

Then  $\hat{\theta} \xrightarrow{p} \theta_0$

Condition (1) is verified according to Lemma 2.2 of [Newey and Mcfadden \(1994\)](#). Condition (2) is verified and guaranteed by the restrictions imposed in the model parameters. Knowing that  $P(S_{jt} = i_0 | S_{1t-1} = i_1, \dots, S_{st-1} = i_s, \mathbf{x}_t)$  is linear combination of a set of  $n$  probabilities and since the logarithm function is a continuous function, condition (3) is verified. Finally, condition (4) is verified according to Lemma 2.4 of [Newey and Mcfadden \(1994\)](#).

Regarding inference, MLE will be asymptotically normal if it is consistent and the following Proposition verifies:

**Proposition 2.** Let  $\{\mathbf{w}_t\}$  be ergodic stationary random variable and let  $s(\mathbf{w}_t; \theta)$  and  $H(\mathbf{w}_t; \theta)$  be the first and second partial derivatives of the  $\log f(\mathbf{w}_t | \theta)$ , respectively. Suppose the estimator  $\hat{\theta}$  is consistent and suppose, further, that

1.  $\theta_0$  is in the interior of  $\Theta$ ,
2.  $\log f(\mathbf{w}_t | \theta_0)$  is twice continuously differentiable in  $\theta$  for any  $\mathbf{w}_t$ ,
3.  $\frac{1}{\sqrt{n}} \sum_{t=1}^n s(\mathbf{w}_t; \theta_0) \xrightarrow{d} N(0, \Sigma)$ , where  $\Sigma$  is positive definite,
4. For some neighborhood of  $\mathcal{N}$  of  $\theta_0$ ,

$$E[\sup_{\theta \in \mathcal{N}} \|H(\mathbf{w}_t; \theta)\|] < \infty$$

so that for any consistent estimator  $\tilde{\theta}$ ,  $\frac{1}{n} \sum_{t=1}^n H(\mathbf{w}_t; \tilde{\theta}) \xrightarrow{p} E[H(\mathbf{w}_t; \theta)]$  v.  $E[H(\mathbf{w}_t; \theta_0)]$  is nonsingular.

Then  $\hat{\theta}$  is asymptotically normal with

$$Avar(\hat{\theta}) = \{E[H(\mathbf{w}_t; \theta_0)]\}^{-1} \Sigma \{E[H(\mathbf{w}_t; \theta_0)]\}^{-1}$$

Condition (1) is verified as in condition (2) of Proposition (1). Condition (2) is also verified as in condition (3) of Proposition (1), since the logarithm function is twice continuously differentiable. Condition (3) is verified according to the Ergodic Stationary Martingale Differences CLT Billingsley (1961). In this case,  $\Sigma = E[s(\mathbf{w}_t; \theta_0)s(\mathbf{w}_t; \theta_0)'] = -E[H(\mathbf{w}_t; \theta_0)]$ , which implies that  $Avar(\hat{\theta}) = -\{E[H(\mathbf{w}_t; \theta_0)]\}^{-1}$ . Condition (4) is verified according to Lemma 2.4 of Newey and Mcfadden (1994). Considering only one equation, let  $\mathbf{q}_t$  be a  $t \times s$  matrix of the probabilities  $P(S_{1t} | S_{1t}, x_t), \dots, P(S_{st} | S_{st}, x_t)$  and  $\lambda$  a row-vector of  $\lambda_{11}, \dots, \lambda_{1s}$ , the hessian matrix is given by  $E[\mathbf{q}_t' \mathbf{q}_t (\lambda \mathbf{q}_t' (\lambda \mathbf{q}_t')^{-1})]$ . Condition (v) is verified if  $E[\mathbf{q}_t' \mathbf{q}_t]$  is nonsingular.

## Bibliography

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